



Growing
ideas
through
networks

Vegetation and drones?

WG 2 – Natural vegetation group

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Funded by the Horizon 2020 Framework Programme
of the European Union

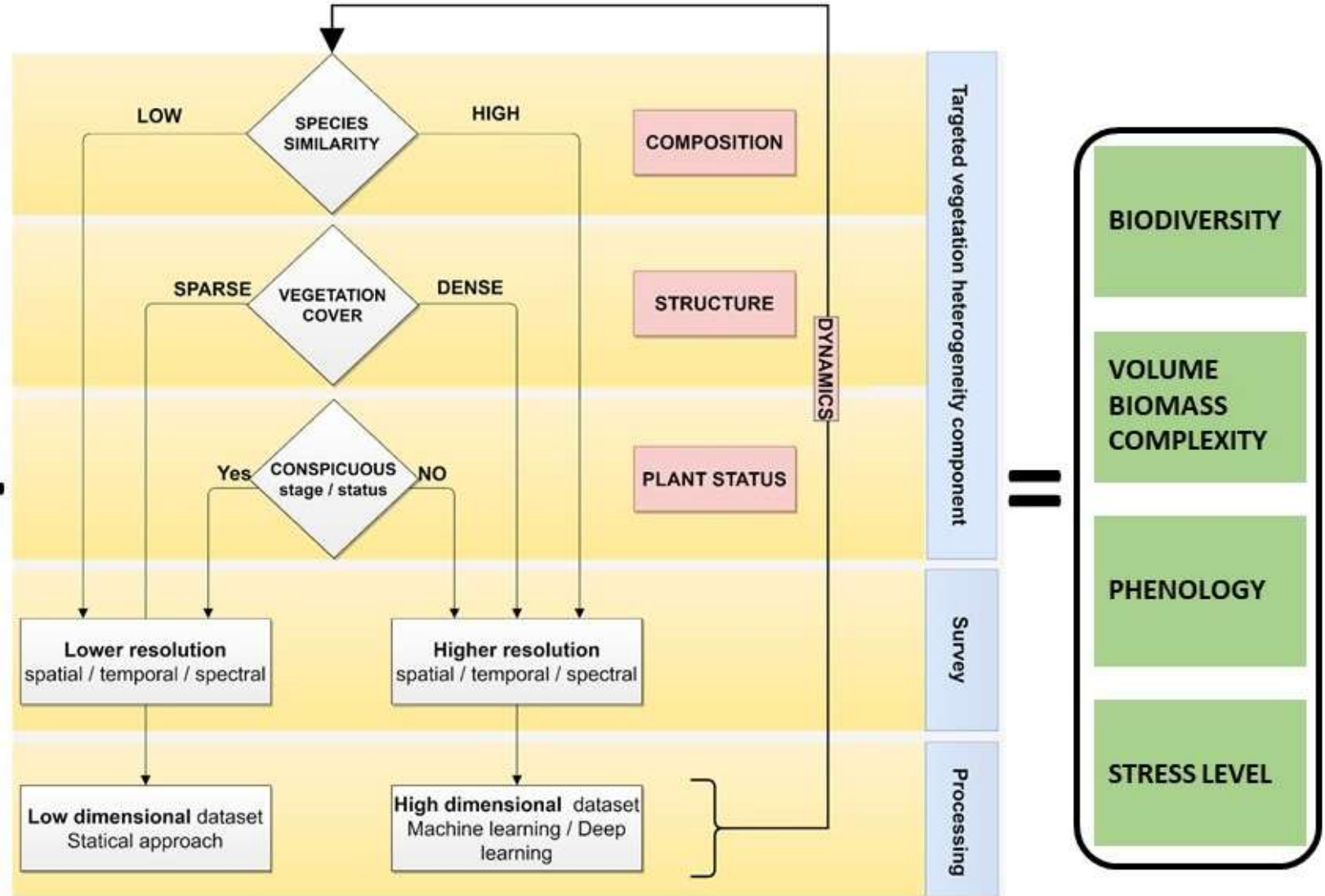
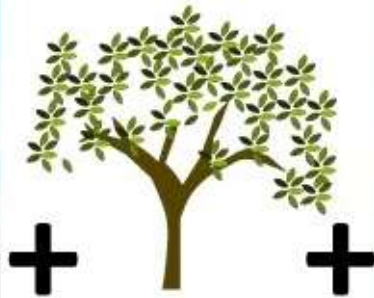


Vegetation and drones? What did we learn

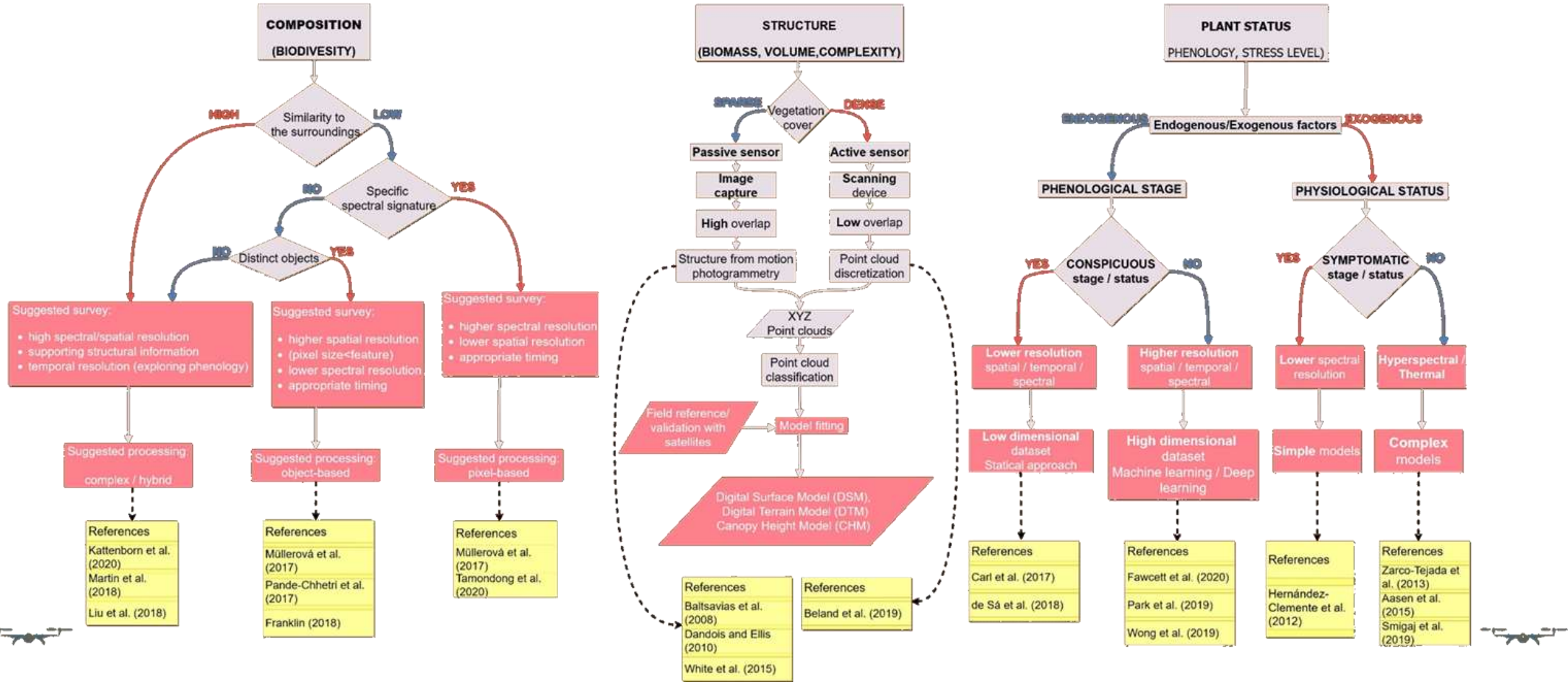


What can drones tell us about natural vegetation?

How to assess ecosystem heterogeneity & complexity?



Choose vegetation characteristics to study with UAS:



J. Müllerová, X. Gago, M. Bučas, J. Company, J. Estrany, J. Fortesa, S. Manfreda, A. Michez, M. Mokoš, G. Paulus, E. Tiškus, M. Tsiadouli & R. Kent (2021): **Characterising vegetation complexity with unmanned aerial systems (UAS) - a framework and synthesis**, Ecological Indicators

<https://www.costharmonious.eu/characterizing-vegetation-complexity-with-uas>

Eyal Ben Dor, Salvatore Manfreda (eds)

Remote Sensing of the Environment using Unmanned Aerial Systems (UAS)



Chapter 5. Vegetation assessment by UAS - current state and perspectives

Authors: Jana Müllerová, Martin Mokroš, Sander Múcher, Gernot Paulus, Tomáš Bartaloš, Martynas Bučas, Joan Estrany, Xurxo Gago, Rafi Kent, Salvatore Manfreda, Maria A. Tsiafouli, Adrien Michez

1. Introduction

2. Methods

2.1 Two-dimensional mapping and monitoring

2.2 Three-dimensional mapping and monitoring

2.3 Novel approaches

2.3.1 Combining or fusing 2D and 3D approaches

2.3.2 Combining with Other Techniques

2.3.3 Machine and Deep Learning

2.3.4 Open source software

3. Vegetation mapping and monitoring, examples of the best practices

3.1 State - mapping biodiversity

Pilot 1. Monitoring plant invasion using consumer camera and OBIA

Pilot 2. Detection of sea grass on Dutch sea coast using Deep Learning

Pilot 3. Temperate forest species mapping using multitemporal imagery

3.2 Structure - assessing stand complexity and biomass

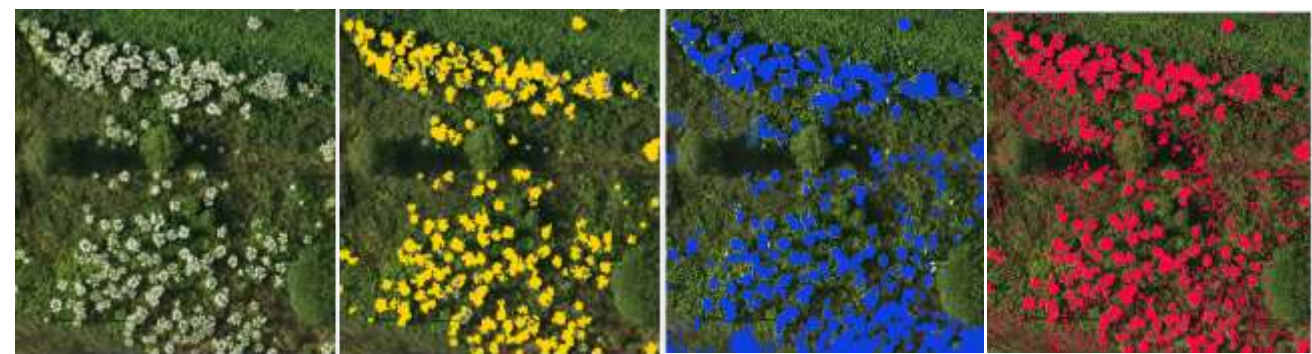
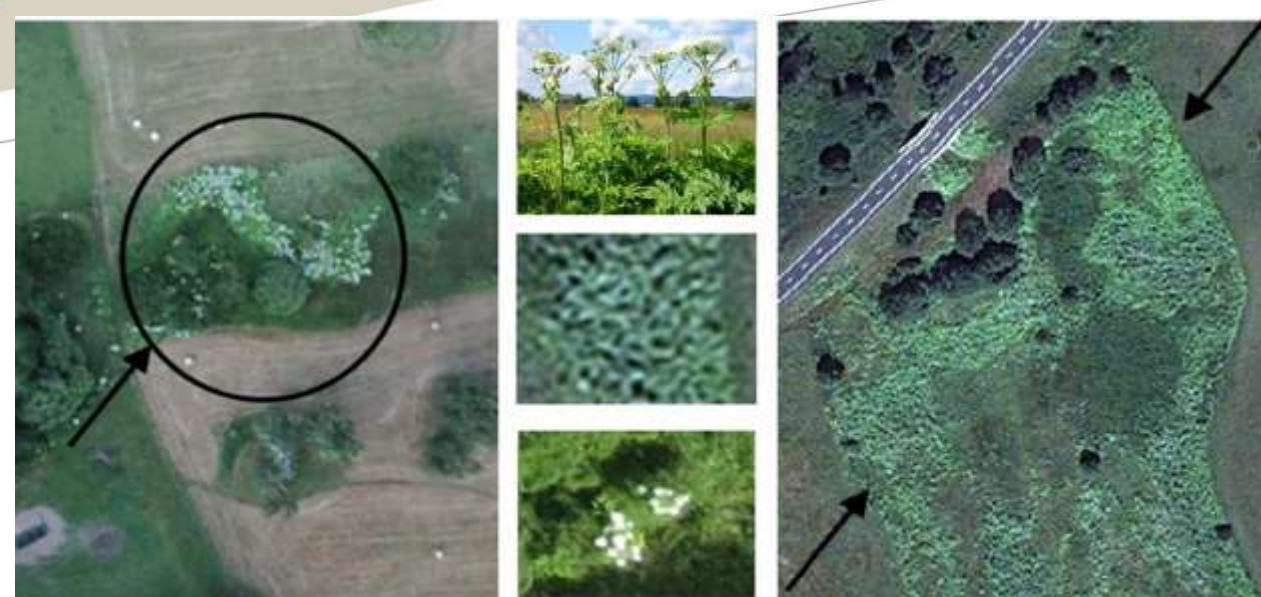
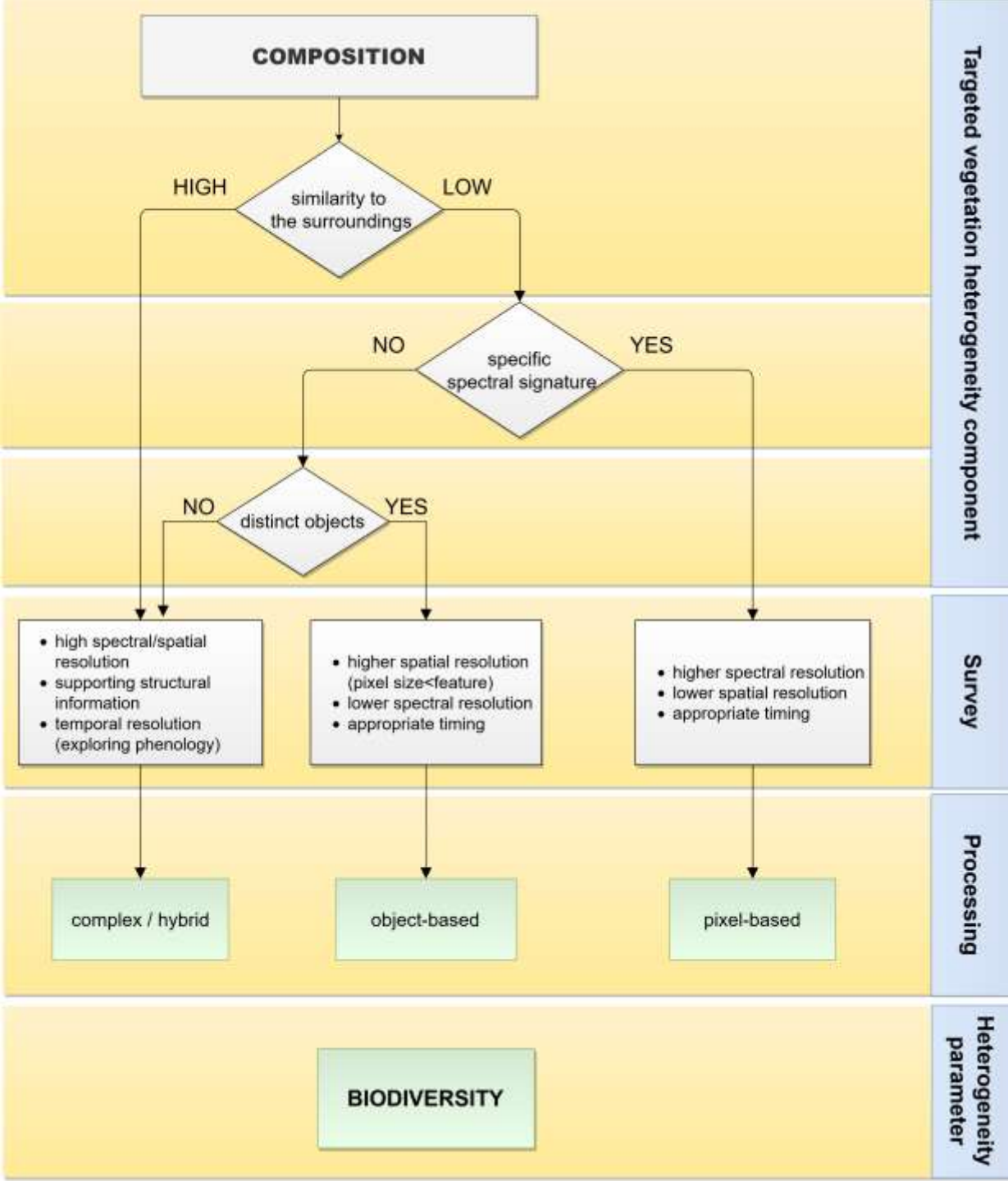
Pilot 4. Sensor Fusion between TLS- and photogrammetric-UAS- derived point clouds

3.3 Status - assessing phenology and stress

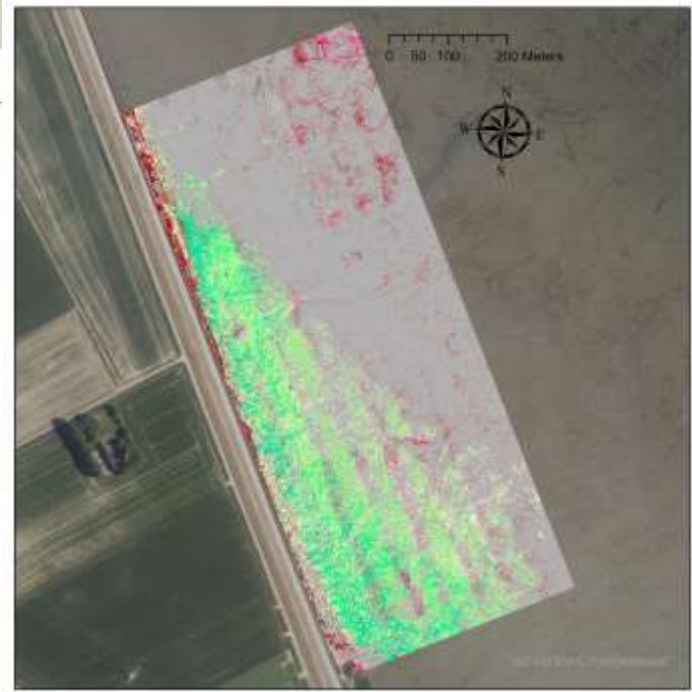
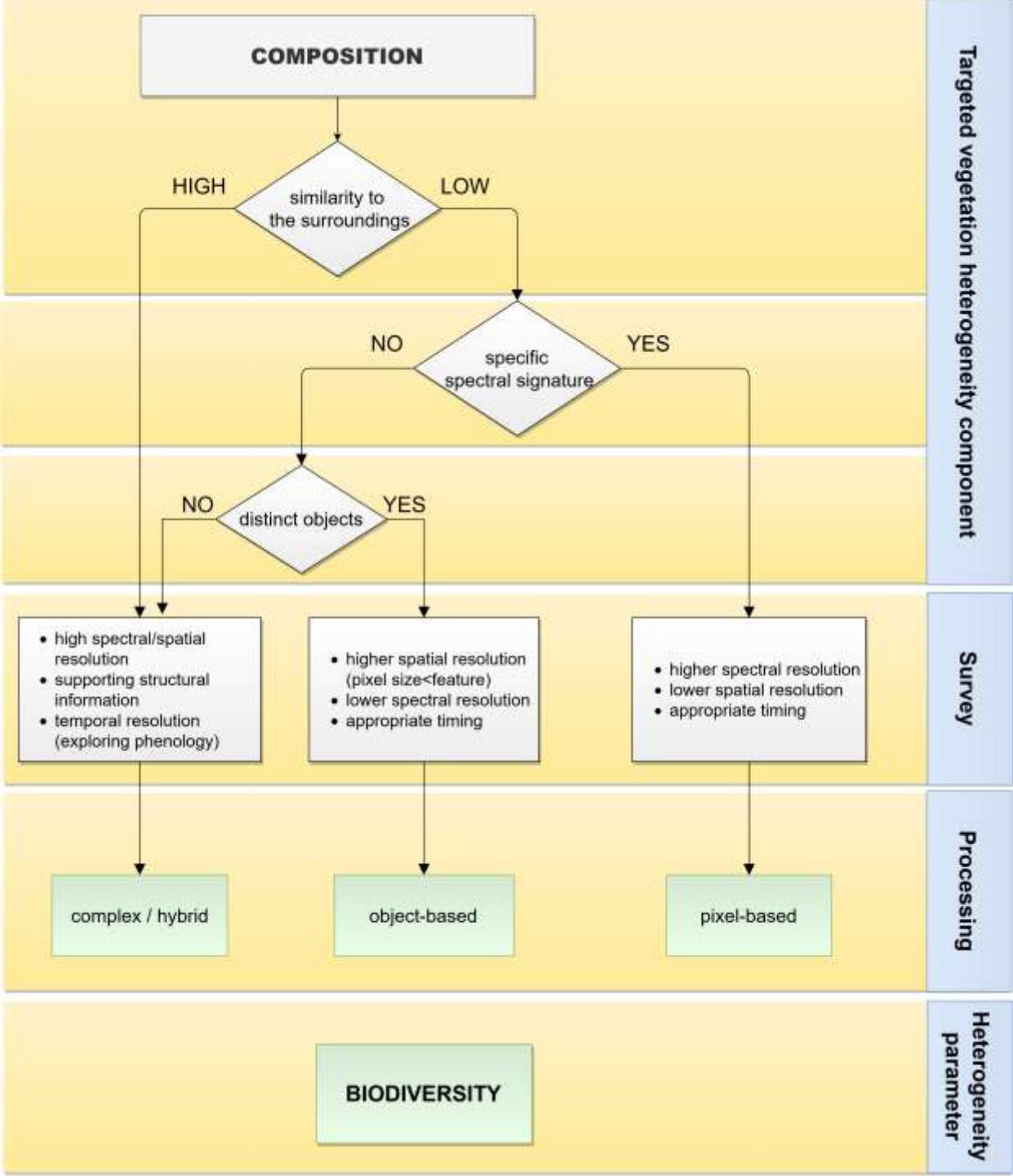
3.4 Dynamics - monitoring the development

Pilot 5. Windthrow detection - comparison of LiDAR and photogrammetry

4. Challenges and perspectives

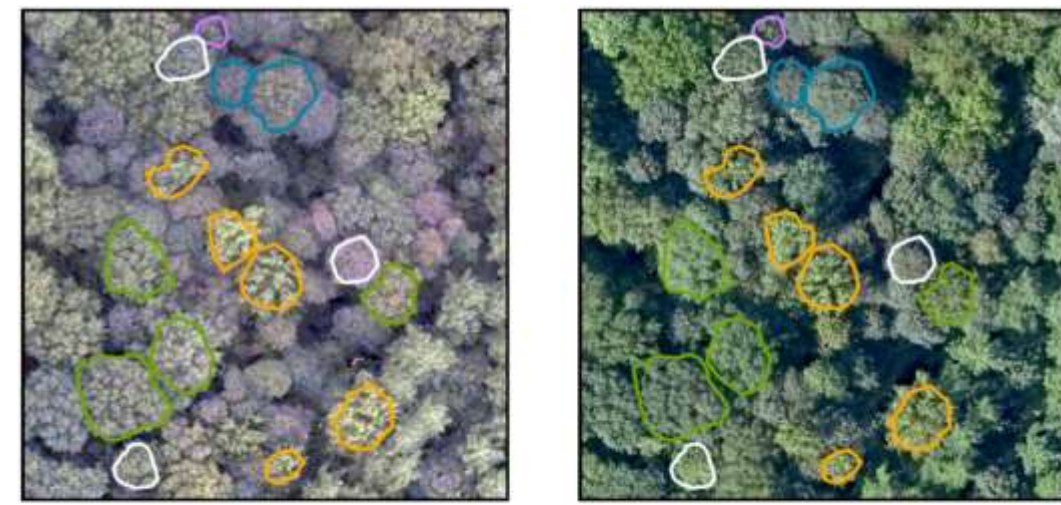
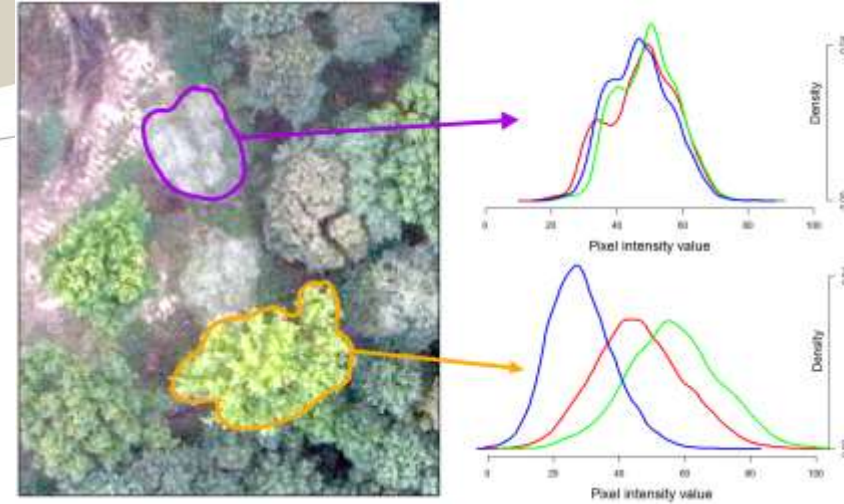
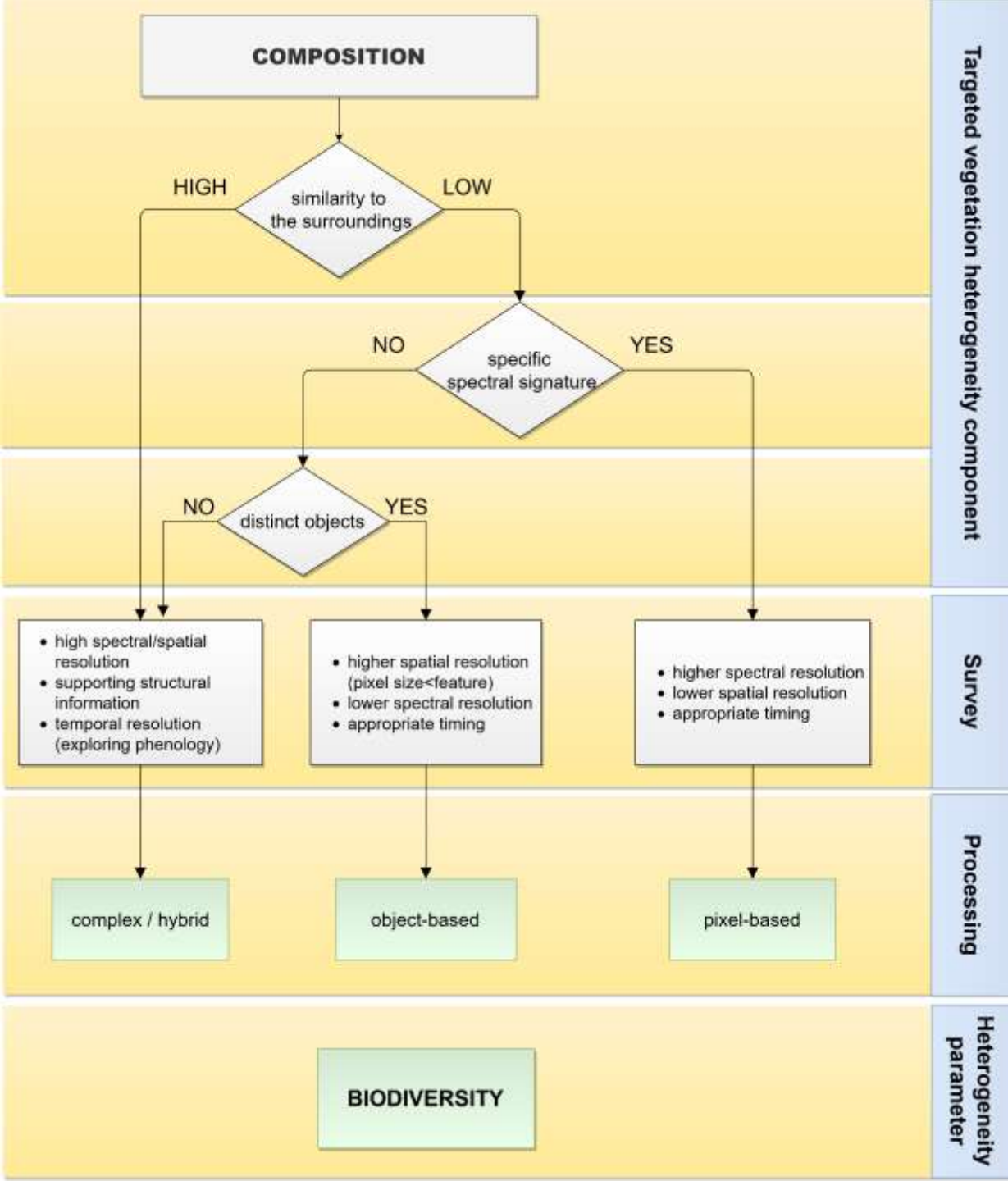


Comparison of different segmentations. From left: original image (RGB); yellow - multiresolution segmentation/RF classifier (eCognition); blue - OrfeoToolbox segmentation (mean_shift) and RF classifier; red - RF pixel-based classifier.



- 1 Brown seaweed
- 2 Green seaweed
- 3 Bare soil
- 4 Dwarf eelgrass 1-25 %
- 5 Dwarf eelgrass 26-50%
- 6 Dwarf eelgrass 51-100%
- 7 Sea lettuce

Deep learning classification of sea grass on Dutch sea coast (Mucher et al. 2020, Wageningen)



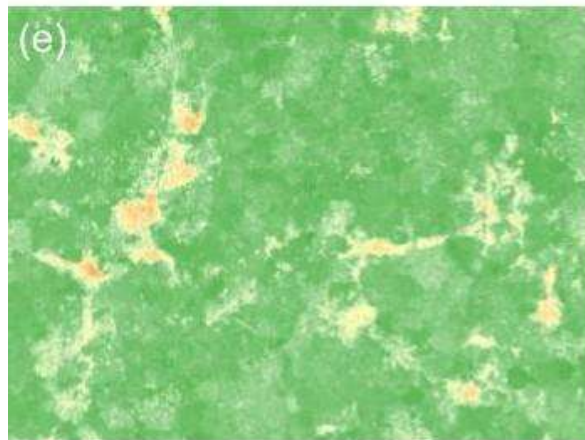
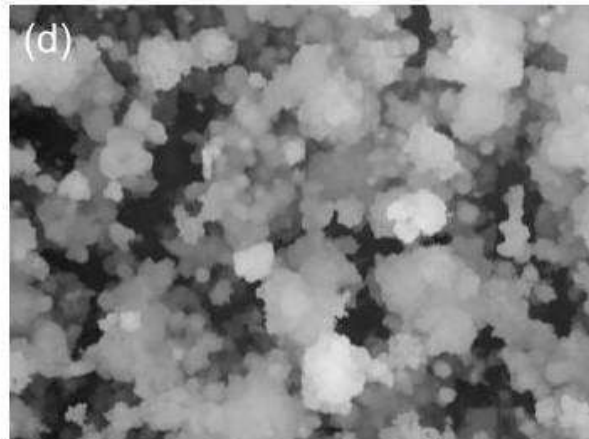
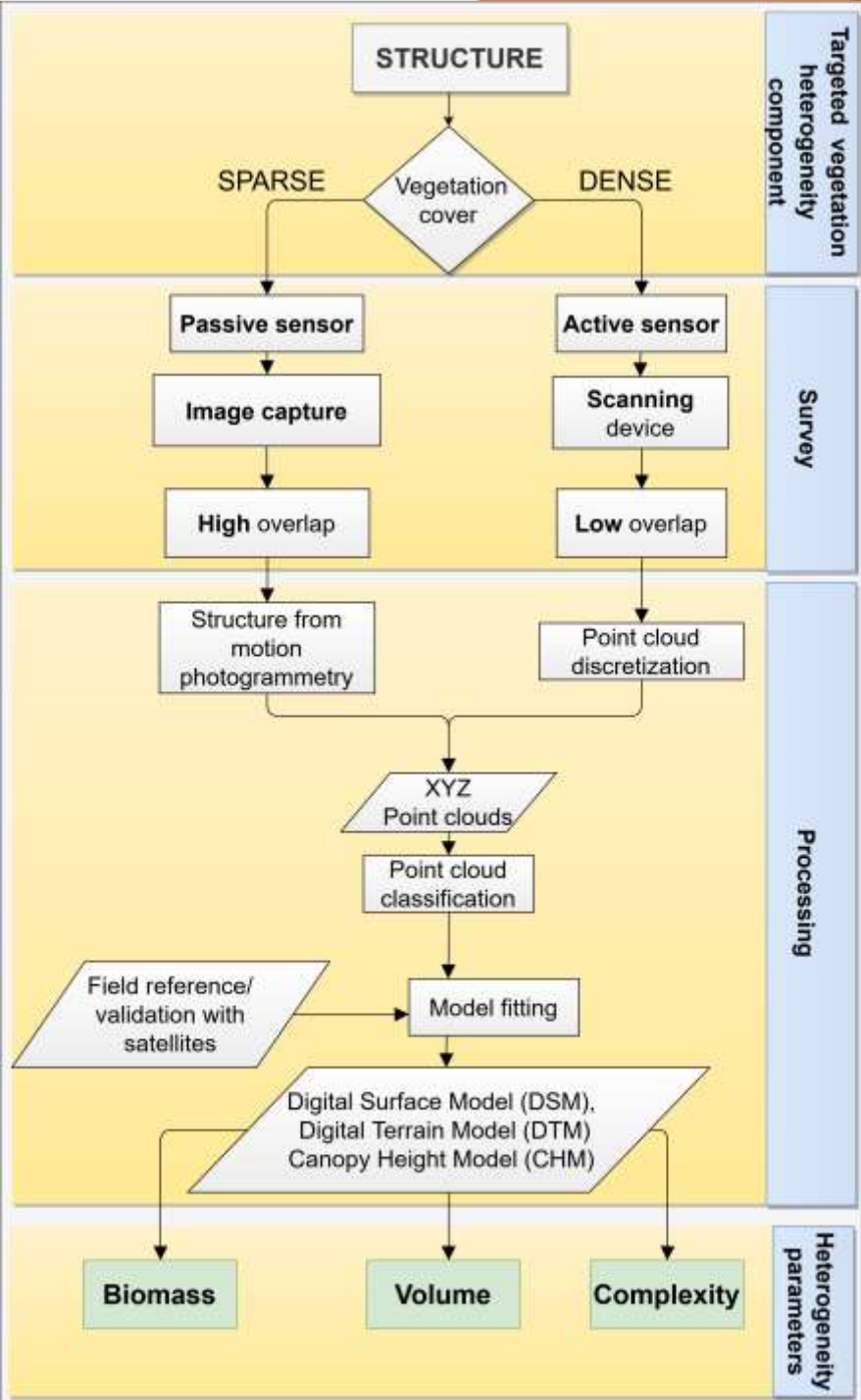
Survey 7

Survey 8

Differences in spectral response captured as a time series with a compact camera mounted on an UAS for two tree crowns (birch and poplar species). English oak: green; poplars: orange; sycamore maple: blue; common ash: white; birches: purple. Lisein et al. (2015) PLoS ONE 10 (11), e0141006

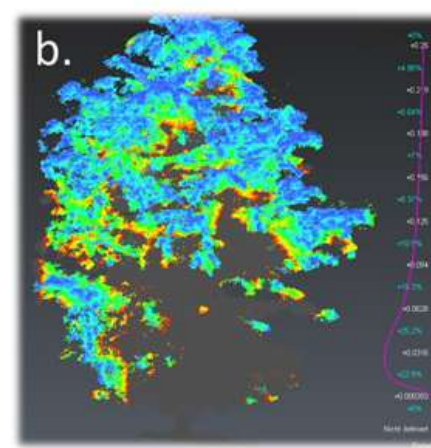
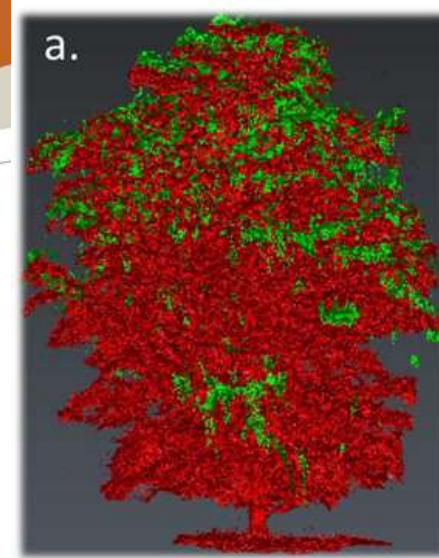
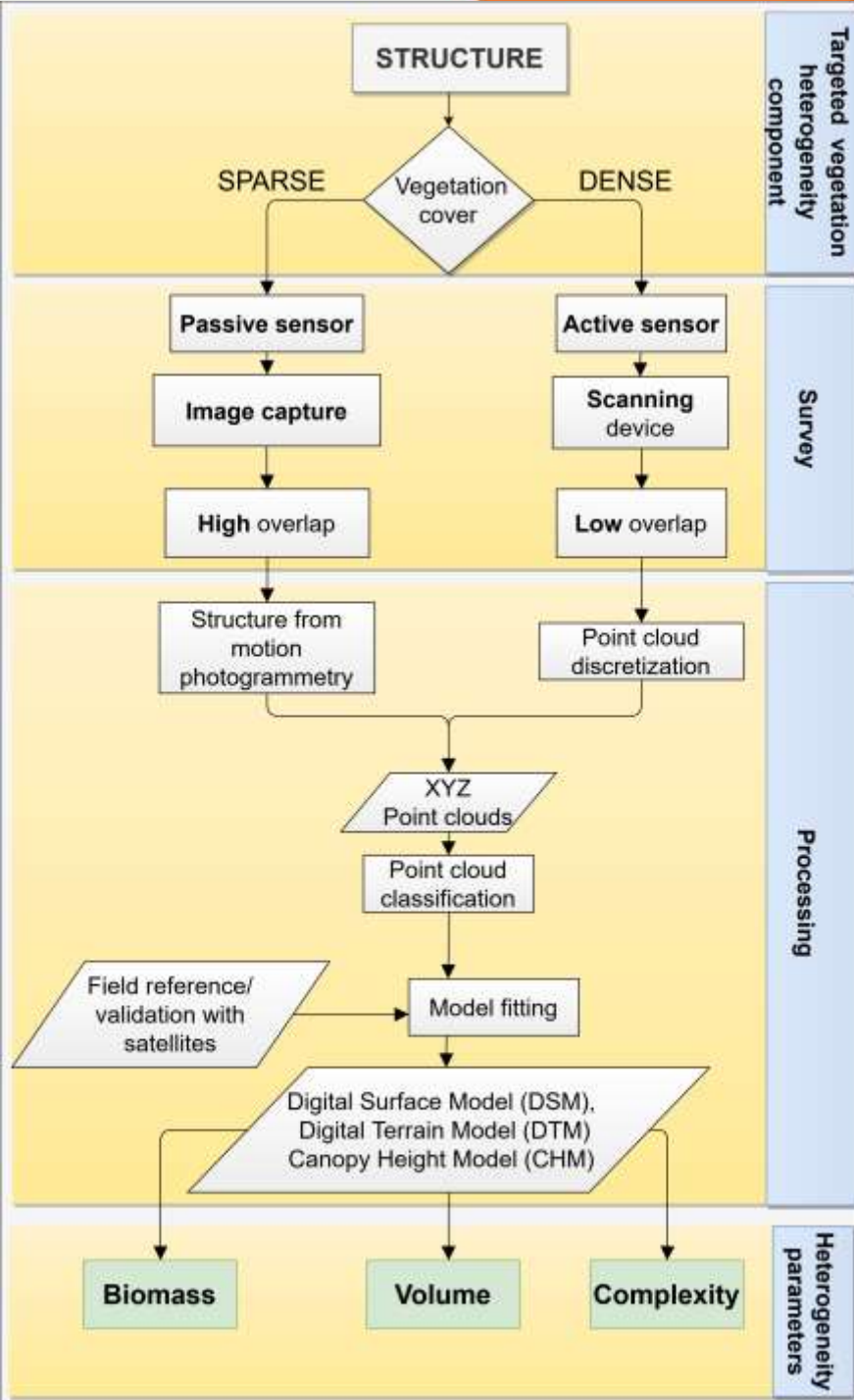
Müllerová et al. (2021). Ecol. Indicators 131, 108156

Müllerová et al. (2022). Remote Sensing of the Environment using Unmanned Aerial Systems (Elsevier, ed. Dor & Manfreda)



Müllerová et al. (2021). *Ecol. Indicators* 131, 108156

Müllerová et al. (2022). *Remote Sensing of the Environment using Unmanned Aerial Systems* (Elsevier, ed. Dor & Manfreda)



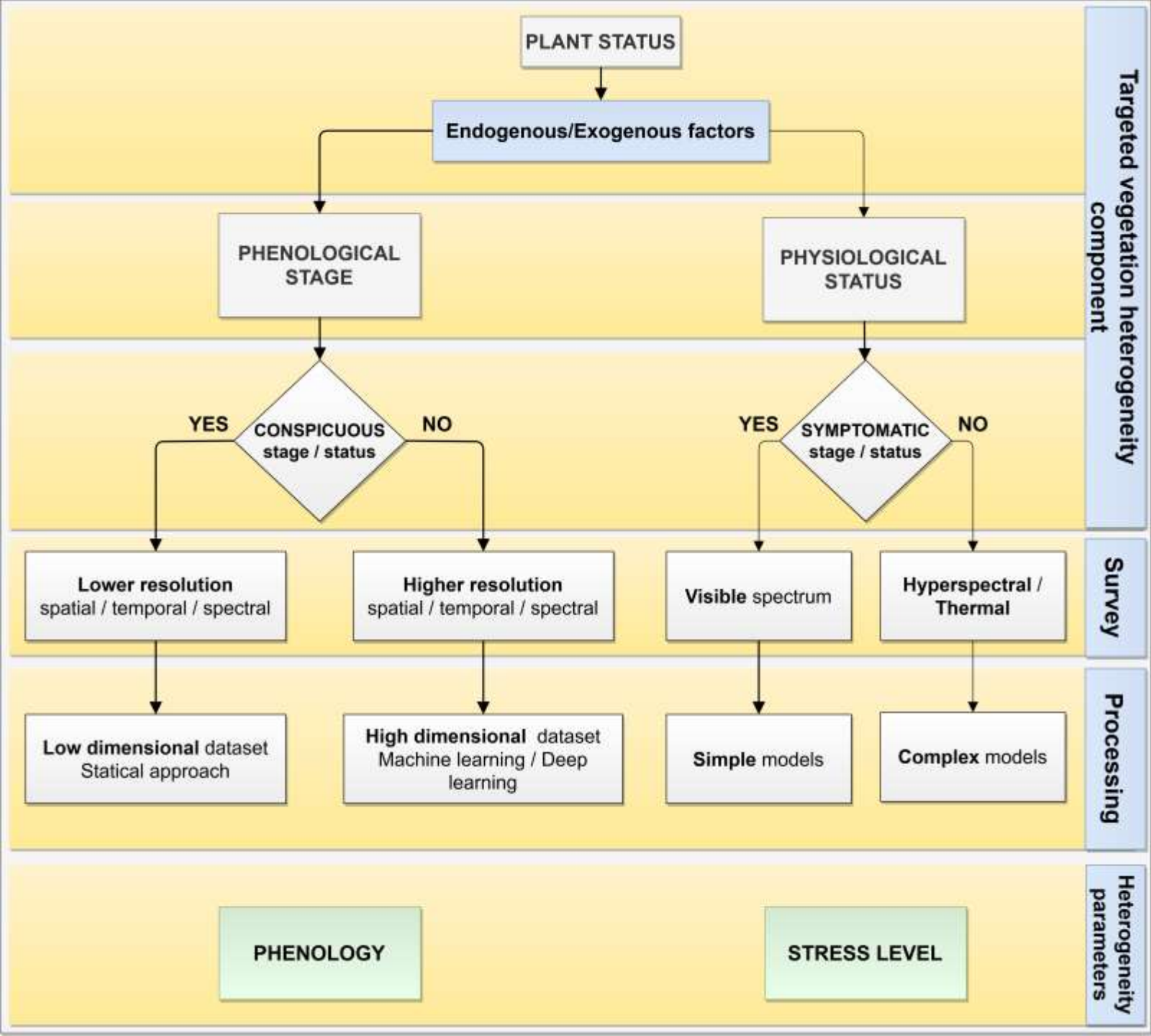
Zebedin (2020) Bcl Theses



Temporary Art Installation FOR FOREST by Klaus Littmann (8. 9 – 27. 10 2019, Klagenfurt, Austria)

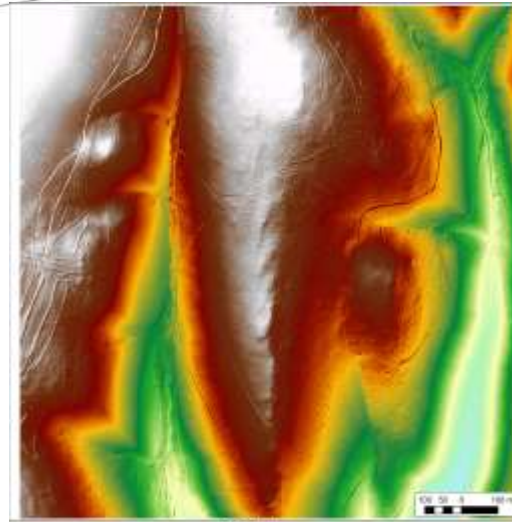


Kainbacher(2020) Bcl Theses

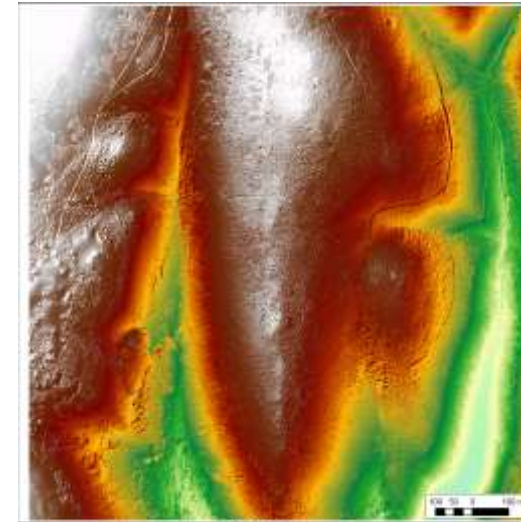


Dynamics - monitoring the development – windthrow damage

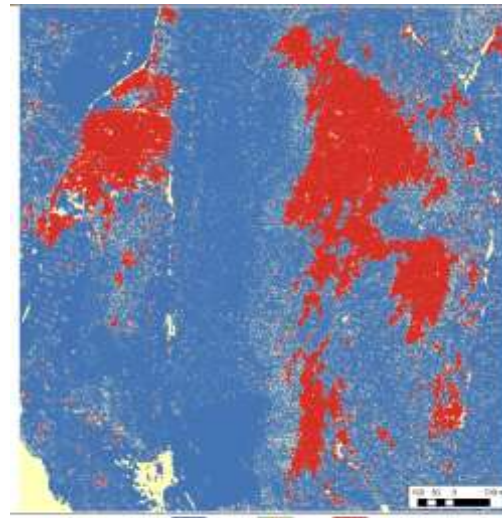
Comparison of ALS and UAV DTM, and windthrow damage detected using a combination of ALS and UAS data



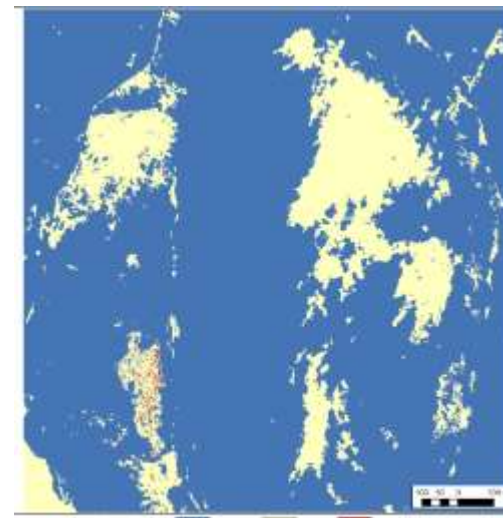
ALS DTM High: 713 Low: 454



UAV DTM High: 713 Low: 454



ALS - UAV -43 - -2 -1 - 1 - 2 - 48 -2 - -1 1 - 2



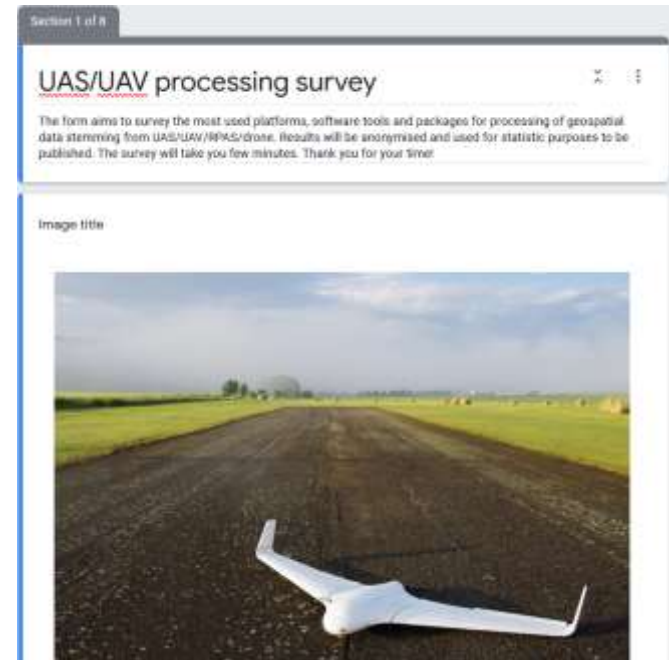
DSM - DTM -46 - -2 -1 - 1 - 2 - 15 -2 - -1 1 - 2

What tools do we use to process UAS data?

...the open source perspective

From free tools preference... ...towards real use

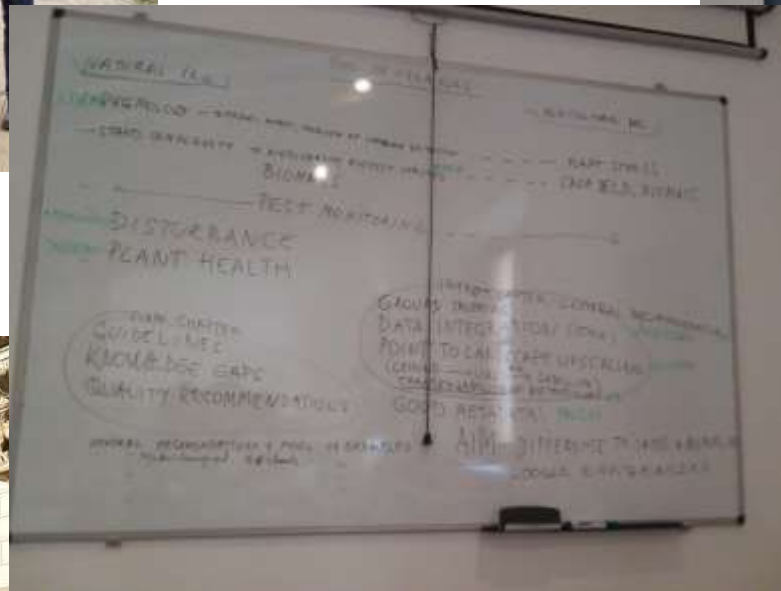
Oh Yes!
IT'S
FREE



T. Bartaloš, J. Brůna, P. Dvořák & J. Müllerová

Challenges and perspectives

- **Technical** – e.g. geometric and radiometric distortions, calibration, improved sensors, standardization of techniques, power of processing algorithms, accuracy assessment.... **common to all drone applications** and are **expected** to be addressed with the technological **advancement**. Still, **imprecisions** of data could be **larger** than some part of **heterogeneity** and subtle **changes** we would like to detect
- **Conceptual** – **perspectives** of drones addressing ecosystem properties greatly **differ** from satellites & field → Mirroring is not enough
- Need for **original research strategies** that would **leverage** on drone data
- Urgent need for **standardized** workflows in drone-assisted ecosystem studies
- Drones are is capable to **expand portfolio** of addressed vegetation types, environmental problems and research questions → **advancements** in technology must go along with **modification of the concepts and paradigms** in vegetation science



HARMONIOUS
UAS for environmental monitoring



Other ongoing HARMONIOUS-related projects

- Heterogeneity review paper
- What are the most important future challenges in drone-based environmental studies? (based on the questionnaire)
- Ecosystem heterogeneity across scales and ecosystems assessed by means of remotely sensed RGB and 3D data (call for data, still not processed...) – this could also be a baseline for a joint research proposal
- Creating maps of soil ecological functioning combining soil biological and UAV data (Maria Tsiafouli)
- Martin Mokroš is leading a **new COST action** „*Three-dimensional forest ecosystem monitoring and better understanding by terrestrial-based technologies*“. Action started 2021



Working groups:

WG1 Laser- and image-based data collection

WG2 Data Fusion

WG3 Laser- and image-based point cloud processing

WG4 Precision Forestry

WG5 Forest Ecology

WG6 Dissemination, knowledge gaps identification and cooperation guidance

Thank you for your attention!

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